

- Useful to change the coordinate system to have simpler bounds when the current bounds are difficult, if impossible to describe and evaluate in the standard Cartesian system.
- Example: transform a region in the xy -plane to the uv -plane (i.e. uv -substitution).
- Generally, transform (x_1, x_2, \dots, x_n) to (u_1, u_2, \dots, u_n) .
- Application of the **Implicit Function Theorem**.
- Come up with a vector-valued function that takes in a vector in one coordinate system and transform it to vector in another coordinate system.
- Don't forget to add the Jacobian! The Jacobian is what allows us to change the coordinate system of the integral - it is what makes change of variables possible!
- Example of change in two variables (can be generalized to n variables):

$$\iint_D f(x, y) dy dx = \iint_S f(u(x, y), v(x, y)) \left| \frac{\partial(x, y)}{\partial(u, v)} \right| dv du$$

- Don't forget to take the absolute value of the Jacobian!
- Common transformations:
 - Cartesian plane to polar plane: $(x, y) \leftrightarrow (r, \theta)$
 - $x = r \cos \theta \quad y = r \sin \theta \quad r^2 = x^2 + y^2 \quad \theta = \tan^{-1}\left(\frac{y}{x}\right)$
 - Cartesian to cylindrical: $(x, y, z) \leftrightarrow (r, \theta, z)$: same as Cartesian to polar.
 - Cartesian to spherical: $(x, y, z) \leftrightarrow (\rho, \theta, \varphi)$
 - $x = \rho \cos \theta \sin \varphi \quad y = \rho \sin \theta \sin \varphi \quad z = \rho \cos \varphi$
 - $\rho^2 = x^2 + y^2 + z^2 \quad \theta = \tan^{-1}\left(\frac{y}{x}\right) \quad \varphi = \tan^{-1}\left(\frac{\sqrt{x^2 + y^2}}{z}\right)$
 - Jacobians for these common transformations:
 - For $(x, y) \leftrightarrow (r, \theta)$:
 - $\frac{\partial(x, y)}{\partial(r, \theta)} = r \quad \frac{\partial(r, \theta)}{\partial(x, y)} = \frac{1}{r} = \frac{1}{\sqrt{x^2 + y^2}}$
 - For $(x, y, z) \leftrightarrow (r, \theta, z)$:
 - $\frac{\partial(x, y, z)}{\partial(r, \theta, z)} = r \quad \frac{\partial(r, \theta, z)}{\partial(x, y, z)} = \frac{1}{r} = \frac{1}{\sqrt{x^2 + y^2}}$
 - For $(x, y, z) \leftrightarrow (\rho, \theta, \varphi)$:
 - $\frac{\partial(x, y, z)}{\partial(r, \theta, \varphi)} = \rho^2 \sin \varphi \quad \frac{\partial(r, \theta, \varphi)}{\partial(x, y, z)} = \frac{1}{\rho^2 \sin \varphi}$